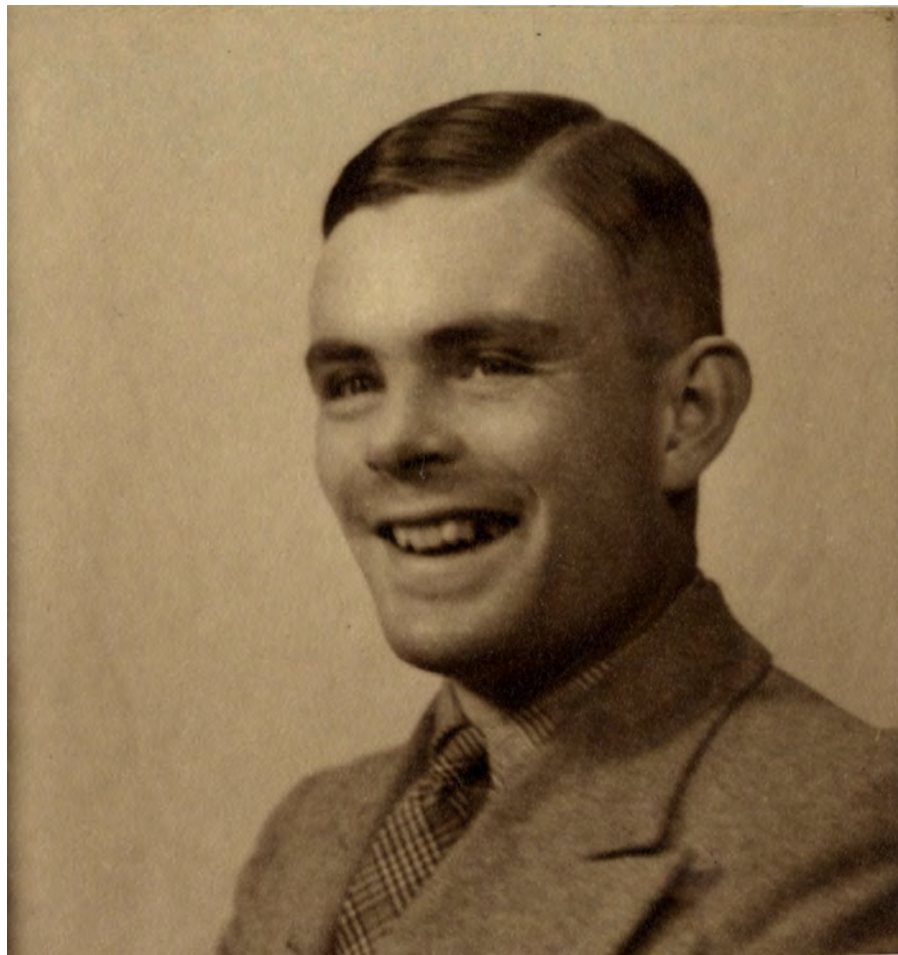


# CONDITION NUMBERS & PROBABILITY for EXPLAINING ALGORITHMS

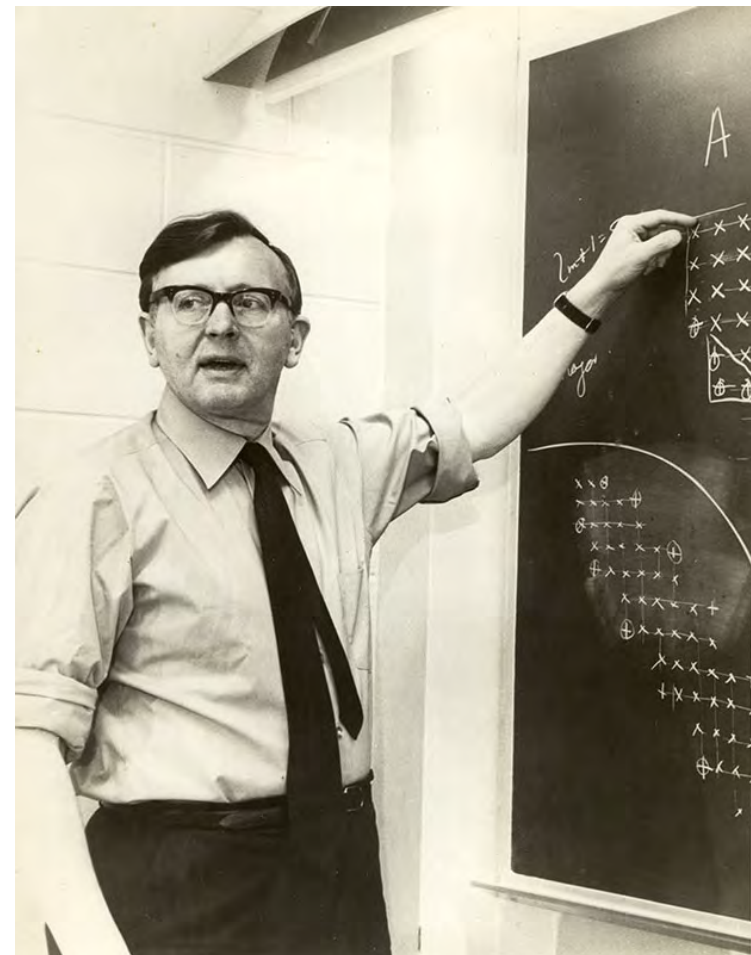
Josué  
TONELLI-CUETO

# A Foundational Myth

Turing vs. Wilkinson



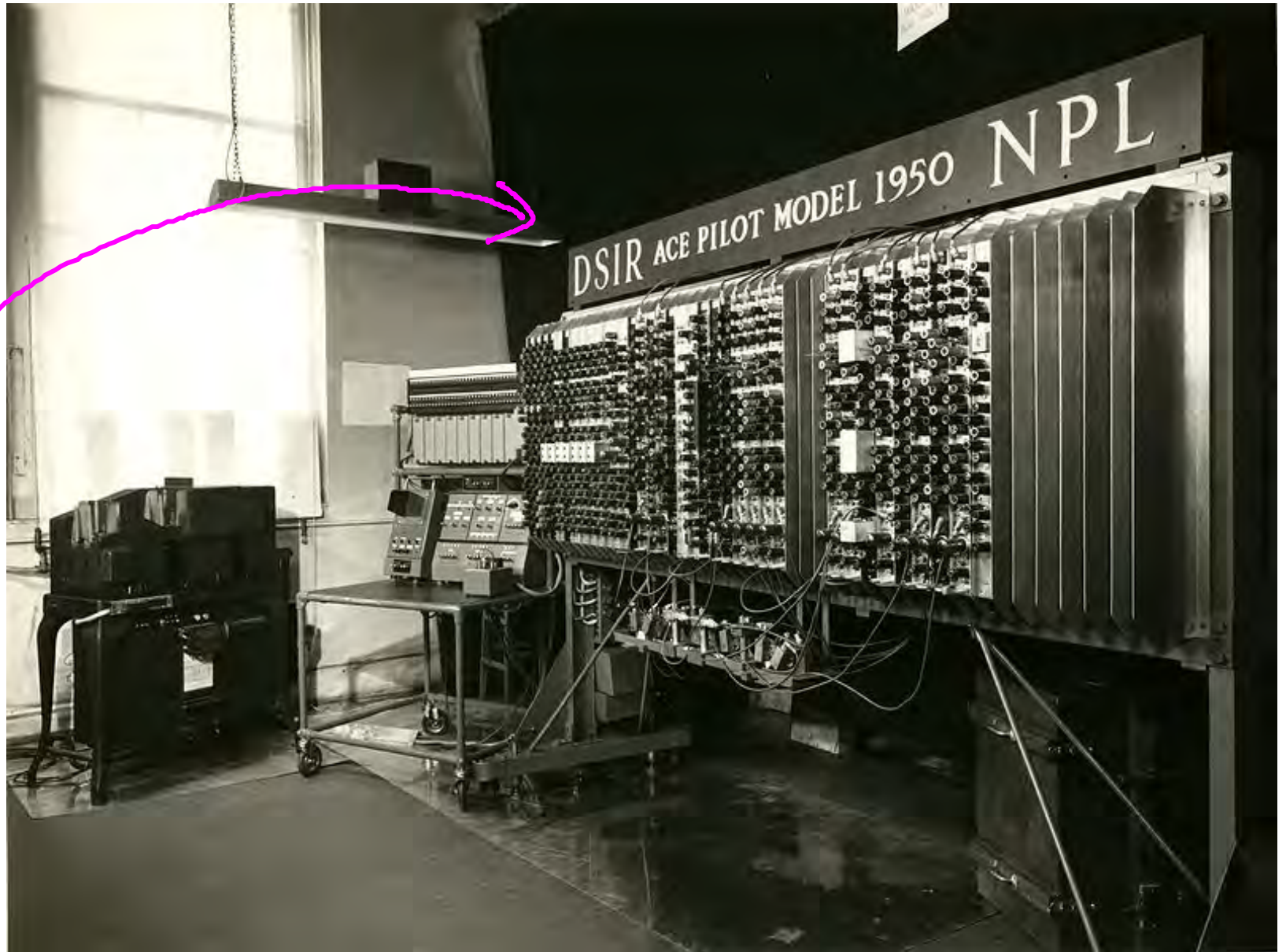
Source: King's College  
[ATM/K/7/11]



Source: U. of Manchester

Source: 1970 Turing Lecture

We are in 1946...  
at the NPL in Manchester



The computer  
4 years after!

Source: U. of Manchester

However, it happened that some time after my arrival, a system of 18 equations arrived in Mathematics Division and after talking around it for some time we finally decided to abandon theorizing and to solve it. **A system of 18 is surprisingly formidable**, even when one has had previous experience with 12, and we accordingly decided on a joint effort.

Wilkinson, 1970 Turing Lecture



Source: Beryl Turing  
& King's College

Gaussian  
Elimination will  
not work!

It will work!  
Let's do it with  
complete pivoting.



Source: U. of Manchester

And it succeeded!

I suppose this must be regarded as a defeat for Turing since he, at that time, was a keener adherent than any of the rest of us to the pessimistic school.

**ROUNDING-OFF ERRORS IN MATRIX PROCESSES**

*By* A. M. TURING

*(National Physical Laboratory, Teddington, Middlesex)*

[Received 4 November 1947]

The second round undoubtedly went to Turing!

Wilkinson, 1970 Turing Lecture

# Why

do some algorithms  
perform better than predicted?

Not an isolated phenomenon:  
the Simplex Method

Linear Programming  
 $\max c^T x$   
s.t.  $Ax \leq b$

Problem

Danzig (1947)  
Simplex Method

↪ Very efficient in practice,  
but... why?

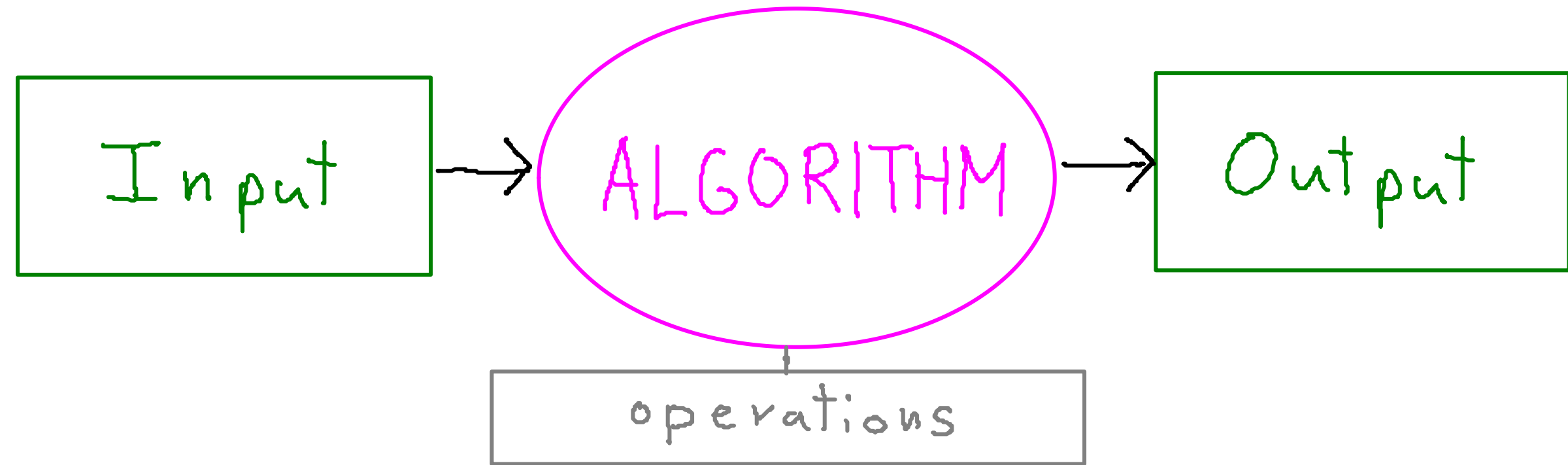
Spielman & Teng (2001)

Justify Simplex Method using smoothed analysis

# Complexity of Algorithms



# Complexity of (Traditional) Algorithms

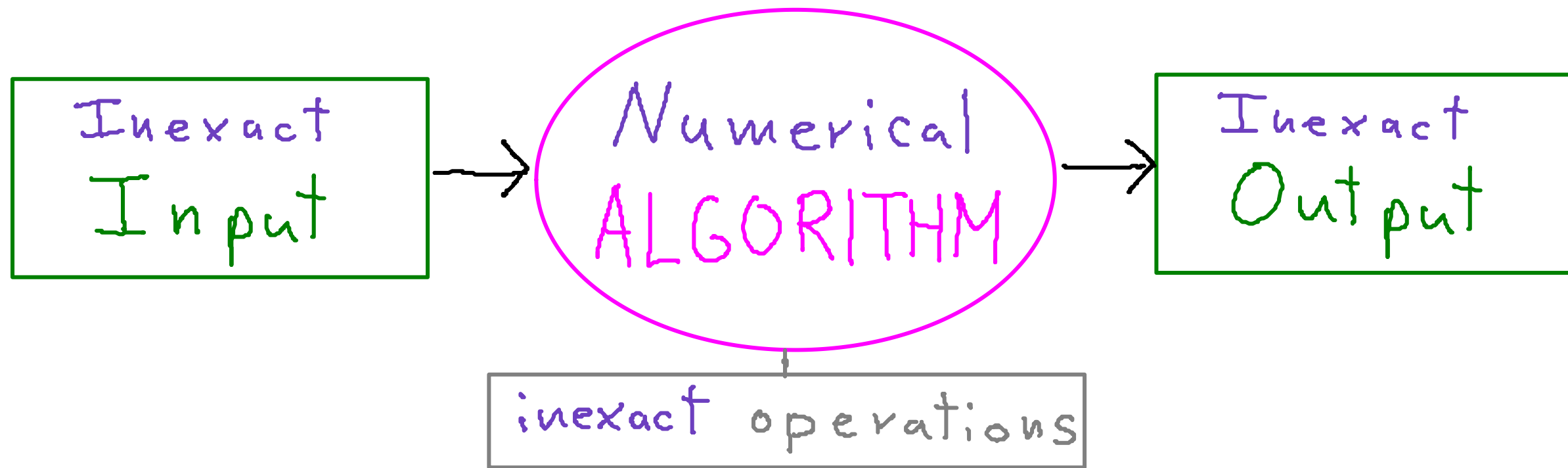


Worst-case form of complexity estimate:

$$\text{run-time}(\text{ALGORITHM}, \text{Input}) \leq f(\text{size}(\text{Input}))$$

⚠ sometimes **size** has several parameters  
(e.g. #variables, degree...)

# Complexity of Numerical Algorithms



⚠ usual form of complexity fails!

ALL INPUTS OF THE SAME SIZE ARE EQUAL,  
BUT SOME INPUTS ARE MORE EQUAL  
THAN OTHERS

# Condition Numbers

(Turing) (Goldstine, von Neumann)

$\text{cond}(\text{Input})$ :


measure of numerical sensitivity of Input

$\text{cond}$  big  $\Rightarrow$

Small variations of Input  
 $\rightarrow$  big variations of Output

$\text{cond}$  small  $\Rightarrow$

'big' variations of Input  
 $\rightarrow$  small variations of Output

  $\text{cond}$  is a property of the computational problem,  
not of the algorithm!

# Turing Condition Number

$$A \in \mathbb{C}^{n \times n}$$

$$\text{cond}(A) := \|A\| \|A^{-1}\|$$

Linear System:  $Ax = b$

$$\text{rel-error}(x) \lesssim \text{cond}(A) \max\{\text{rel-error}(A), \text{rel-error}(b)\}$$

# Condition-based Complexity

(Turing) (Goldstine, von Neumann)

$$\text{run-time}(\text{ALGORITHM}, \text{Input}) \leq f(\text{size}(\text{Input}), \text{cond}(\text{Input}))$$

Can we have

a complexity estimate

of a numerical algorithm

only depending on size?

# Randomize your Input

(Goldstine & von Neumann) (Smale) (Demmel)

Random Input  $\rightarrow$  Probabilistic Complexity



How do we randomize the Input?

Choice depends on the context!

# Probabilistic Complexity

(Goldstine & von Neumann) (Smale) (Demmel)

$$P_{\text{input}}[\text{run-time}(\text{ALGORITHM}, \text{input}) \geq t] \leq f(s, t)$$

where  $\text{size}(\text{input}) \leq s$

...and if we are lucky

$$E_{\text{input}}[\text{run-time}(\text{ALGORITHM}, \text{input})] \leq f(s)$$

# Smoothed Complexity

(Spielman & Teng)

$$\sup_{\substack{\text{Input} \\ \text{size}(\text{Input})=S}} \mathbb{P}_{\text{noise}} \left[ \text{runtime}(\text{ALGORITHM}, \text{Input} + \sigma \text{noise}) \geq t \right] \leq f(S, t, \sigma)$$

... and if we are lucky

$$\sup_{\substack{\text{Input} \\ \text{size}(\text{Input})=S}} \mathbb{E}_{\text{noise}} \left[ \text{runtime}(\text{ALGORITHM}, \text{Input} + \sigma \text{noise}) \right] \leq f(S, \sigma)$$



# Why Smoothed is better?

Worst-case form of complexity estimate

$$\text{run-time}(\text{ALGORITHM}, \text{Input}) \leq f(\text{size}(\text{Input}))$$

$$\uparrow \sigma \rightarrow 0$$

Smoothed form of complexity estimates

$$\sup_{\substack{\text{Input} \\ \text{size}(\text{Input})=s}} \mathbb{P}_{\text{noise}} \left[ \text{run-time}(\text{ALGORITHM}, \text{Input} + \sigma \text{noise}) \geq t \right] \leq f(s, t, \sigma)$$

$$\downarrow \sigma \rightarrow \infty$$

Probabilistic form of complexity estimates

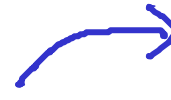
$$\mathbb{P}_{\text{input}} \left[ \text{run-time}(\text{ALGORITHM}, \text{input}) \geq t \right] \leq f(s, t)$$

# Where to find all the details?

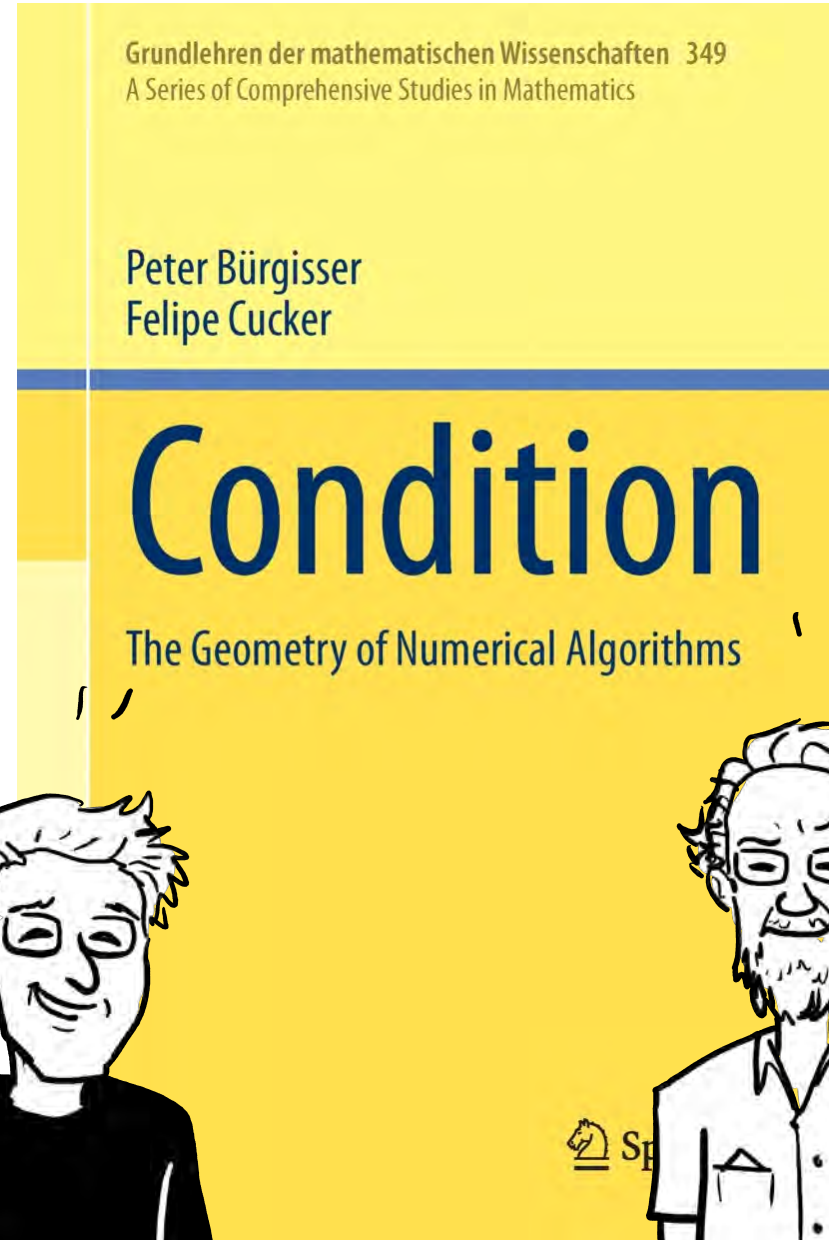
Linear Systems



Systems of Polynomial Equations



Linear Programming (Interior Point Method)



Peter Bürgisser



Felipe Cucker

Drawings by Jorge Cham

# A Case Study

of the Framework in Action;

the DESCARTES Solver

For Finding Real Roots

of real univariate polynomials

Joint work of

Elias Tsigaridas

Josué Tonelli-Cueto



Alperen A. Ergür

Photo while working on this project

# Real Root Isolation I: The Problem

INPUT:

$$f \in \mathbb{Z}[X]$$

OUTPUT:

Intervals  $J_1, \dots, J_k$  s.t.

0)  $J_i = (a_i, b_i)$  with  $a_i, b_i \in \mathbb{Q}$

1)  $Z(f) \cap \mathbb{R} \subseteq \bigcup_{i=1}^k J_i$

2)  $\forall i, \# Z(f) \cap J_i = 1$

INPUT SIZE PARAMETERS:

$d$  : degree of  $f$

$n$  : bit-size of coefficients of  $f$

MEASURE OF RUN-TIME

Bit complexity



We can also handle continuous inputs!

# DESCARTES SOLVER I: Rule of Signs

$V(\mathcal{f}) := \#$  sign variations of  $\mathcal{f}_0, \mathcal{f}_1, \dots$

THM (Descartes' rule of signs)

$$\# Z(\mathcal{f}, \mathbb{R}_+) \leq V(\mathcal{f})$$

Moreover,

$$V(\mathcal{f}) \leq 1 \Rightarrow \text{Equality}$$

COR

$$\# Z(\mathcal{f}, (a, b)) \leq V(\mathcal{f}, (a, b)) := V\left((x+1)^d \mathcal{f}\left(\frac{bx+a}{x+1}\right)\right)$$

$\uparrow$   
 $(0, \infty) \rightarrow (a, b)$   
bijection



Portrait by Frans Hals  
Source: Wikimedia Commons

# DESCARTES SOLVER II:

## Rule of Signs in Action

$(0, \infty)$

$$g = 2X^3 - 9X^2 + 12X - 6$$

$(x+1)^3 g\left(\frac{x}{x+1}\right)$

$g(x+1)$

$(0, 1)$

$$-6 - 6X - 3X^2 - X^3$$

$(1, \infty)$

$$-1 - 3X^2 + 2X^3$$

$(1, 2)$

$$-1 - 3X - 6X^2 - 2X^3$$

$(2, \infty)$

$$-2 + 3X^2 + 2X^3$$

Real Roots of  $g$ :

2.677650698804...

$(2, 3)$

$$-2 - 6X - 3X^2 + 3X^2$$

$(3, \infty)$

$$3 + 12X + 9X^2 + 2X^3$$

# DESCARTES SOLVER III:

## The Descartes' Oracle

1) Overcounting:  $\#Z(\mathcal{g}, J) \leq V(\mathcal{g}, J)$

2) Exactness I:  $V(\mathcal{g}, J) \leq 1 \Rightarrow \text{Equality}$

3) Exactness II:

$$\#Z(\mathcal{g}, D(m(J), cw(J))) \leq k \Rightarrow V(\mathcal{g}, J) \leq k$$

Obreshkoff's Thm: **DESCARTES** sees the complex roots around!

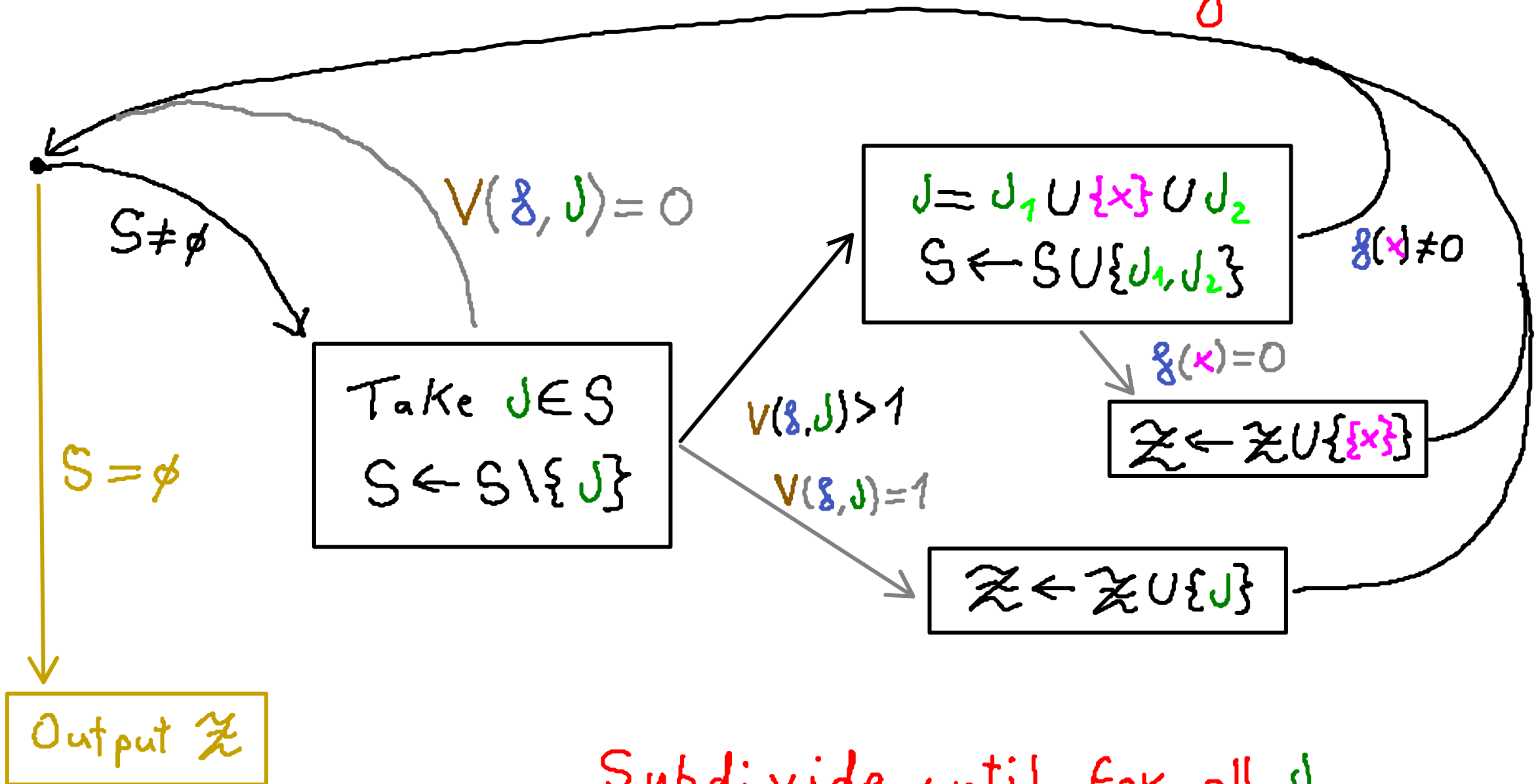
4) Subadditivity:

$$\dot{\cup} J_i \subseteq J \Rightarrow \sum V(\mathcal{g}, J_i) \leq V(\mathcal{g}, J)$$



# DESCARTES SOLVER IV

## The Algorithm



Subdivide until for all  $J$ ,  
 $V(\delta, J) \leq 1$ !

# Real Root Isolation II:

## The State of the Art

STURM SOLVER

$$\tilde{\mathcal{O}}_B(d^4 \gamma^2)$$

DESCARTES SOLVER

$$\tilde{\mathcal{O}}_B(d^4 \gamma^2)$$

ANewDsc

$$\tilde{\mathcal{O}}_B(d^3 + d^2 \gamma)$$

(Sagraloff & Mehlhorn; 2016)

PAN'S ALGORITHM

$$\tilde{\mathcal{O}}_B(d^2 \gamma)$$

(Pan; 2002)

Q: Can we beat the champion?

# Real Root Isolation III:

What do we wish?

$$\tilde{\Theta}_B(d\gamma)$$

We wish to find real roots  
almost as fast as we read the polynomial!

# Real Root Isolation IV:

Are we being pessimistic?

DESCARTES SOLVER

seems to behave faster in practice!

Why?

SPOILER:

DESCARTES

is almost-optimal on average!

What do we mean?

# Real Root Isolation V:

Beyond pessimism

$$\mathbb{E}_g \{ \text{cost}(\text{SOLVER}, g) \mid \text{bit-size}(g) \leq \tau, \text{deg}(g) \leq d \}$$

What's a 'good' random model for  $g$ ?

↑  
Many choices of randomness 😱

# Beyond pessimism I:

## Uniform Random Bit Polynomials & A SIMPLE MAIN THEOREM

$$F = \sum_{k=0}^d F_k X^k$$

s.t.  $F_k \sim \mathcal{U}([-2^\tau, 2^\tau] \cap \mathbb{Z})$  independent

SIMPLE MAIN THM

$$\mathbb{E} \text{cost}(\text{DESCARTES}, F) = \tilde{O}_B(d^2 + d\tau)$$

On average, DESCARTES is almost optimal!

# Beyond pessimism II:

## Random Bit Polynomials

$$F = \sum_{k=0}^d F_k X^k \in \mathbb{Z}[X]$$

bit-size of  $F$ : s.t.  $F_k$  independent

$$\tau(F) := \min\{\tau \mid \forall k, \mathbb{P}(|F_k| \leq 2^\tau) = 1\}$$

weight of  $F$ :

$$w(F) := \max\{\mathbb{P}(F_k = c) \mid c \in \mathbb{R}, k \in \{0, \overset{\downarrow}{d}\}\}$$

No middle indexes!

uniformity of  $F$ :  $u(F) := \ln(w(F)(1 + 2^{\tau(F)+1}))$



# Beyond pessimism III:

## MAIN THEOREM

### MAIN THM

$$\mathbb{E} \text{cost}(\text{DESCARTES}, f) = \tilde{O}_B(d^2 + d\tau)(1 + u(f))^4$$

Note:  $f$  uniform  $\Rightarrow u(f) = 0$

Claim: For many cases,  $u(f) = \mathcal{O}(1)$

IF  $\tau = \Omega(d)$ , almost like reading!

On average, DESCARTES is almost optimal!

# Beyond pessimism IV:

## Examples of Random Bit Polynomials I

- Support control  $\{a, d\} \subseteq A$

$$F = \sum_{k \in A} f_k X^k \quad \text{with } f_k \sim \mathcal{U}([-2^\tau, 2^\tau] \cap \mathbb{Z})$$

... then  $u(F) = 0$

- Sign control  $\sigma \in \{-1, +1\}^{\{0, \dots, d\}}$

$$F = \sum_{k=0}^d f_k X^k \quad \text{with } f_k \sim \mathcal{U}(\sigma_k([1, 2^\tau] \cap \mathbb{N}))$$

... then  $u(F) \leq \ln 3$

Beyond pessimism V:

Examples of Random Bit Polynomials II

- Exact bitsize

$$F = \sum_{k=1}^d F_k X^k \text{ with } F_k \sim \mathcal{U}(\{n \in \mathbb{Z} \mid \lfloor \log n \rfloor = r\})$$

... then  $u(F) \leq \ln 3$

+ their combinations

Our random model is flexible!

# Beyond pessimism V:

Smoothed case included!

$F = \sum_{k=1}^d F_k X^k$  random bit polynomial

$g = \sum_{k=1}^d g_k X^k$  fix polynomial

$\sigma \in \mathbb{Z} \setminus \{0\}$  of entries of size  $\tau$

Then:

$F_\sigma = g + \sigma F$  random bit polynomial  
&  $u(F_\sigma) \leq 1 + u(F) + \max\{\tau - \tau(F), \tau(\sigma)\}$

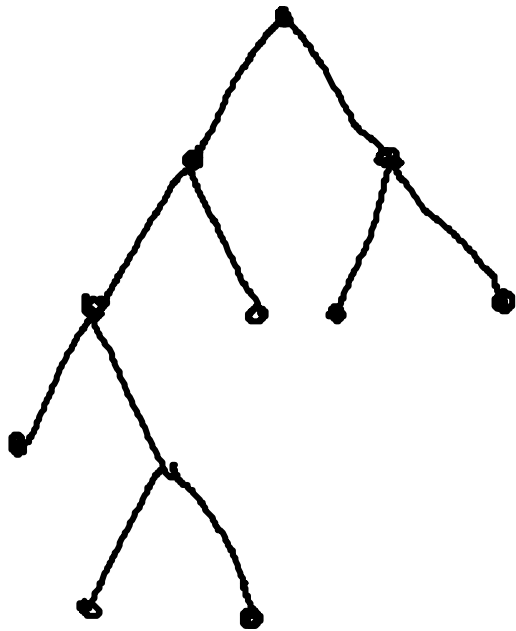
SUMMING UP:

DESCARTES

is almost-optimal on average!

# The Ingredients of the Analysis 0: DESCARTES' tree

$\Upsilon(\mathcal{S}, \mathcal{I})$



run-time of  $DESCARTES(\mathcal{S}, \mathcal{I})$



size of  $\Upsilon(\mathcal{S}, \mathcal{I})$



$\text{depth}(\Upsilon(\mathcal{S}, \mathcal{I}))$   $\text{width}(\Upsilon(\mathcal{S}, \mathcal{I}))$

We only need to control the size of subdiv. tree!

# The Ingredients of the Analysis I: Condition Numbers

$$C(f) := \max_{x \in [-1, 1]} \frac{\sum_{k=0}^d |f_k|}{\max\{|f(x)|, |f'(x)|/d\}}$$

$C(f) = \infty \iff f$  has a singular root in  $[-1, 1]$

Upper bounds on  $C(f)$

→ Lower bounds for root separation of  $f$

→ Upper bounds for depth of DESCARTES' tree

# The Ingredients of the Analysis II: Bounds for Number of Complex Roots

Upper bounds for

# complex roots of  $g$  around  $[-1, 1]$

We only care  
about nearby roots!



Upper bounds

for width of DESCARTES' tree



# The Ingredients of the Analysis III: Probabilistic Toolbox

Ball's smoothing:

$x \in \mathbb{Z}^N$  discrete random variable

$y \in \mathbb{R}^N$  s.t.  $y_i \sim \mathcal{U}((-1/2, 1/2))$  i.i.d.

Then:  $x + y$  continuous random var.

We can use our old cont. toolbox!

⚠ I am omitting a lot of technical details.

TAKE HOME MESSAGE:

to EXPLAIN

the SUCCESS of some ALGORITHMS,

we need

CONDITION NUMBERS & PROBABILITY

to avoid PESSIMISTIC ESTIMATES

Eskerririk Asko

zure arretagatik!

Transl.: Thank you for your attention!